

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	49812	(detect\$3 or monitor\$3 or track\$3) near4 (boundar\$3 or space)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:38
L2	588537	(first or second) near3 (space or position or coordinat\$3)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:34
L3	69299	compar\$5 with (distance or coordinates)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:35
L4	906	1 and 2 and 3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:36
L5	7382	(predetermined or predefined or preselected) near2 (fixed near2 (position or coordinate))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:07
L6	8	4 and 5	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:37
L7	305108	(detect\$3 or monitor\$3 or track\$3) near9 (individual or person or animal or pet or object)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:39
L8	288	4 and 7 and boundar\$3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:20
L12	5	8 and 5	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:07
L13	88	8 and (fixed near2 (position or coordinate))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:13
L14	13	("6518919") or ("6480147") or ("6441778") or ("6421001") or ("6236358") or ("6388612") or ("6362778") or ("6172640") or ("5905461")) PN.	USPAT; EPO; JPO; DERWENT	OR	OFF	2005/06/21 11:14
L15	0	14 and 7 and 5 and boundar\$3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21
L16	7	14 and 7 and boundar\$3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21
L17	6	16 and 3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21
L18	2	17 and 2	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21

US 5774826 A	Optimization of survey	701/207	342/357.01; 342/457; 701/213
US 6888953 B2	Vehicle surroundings	382/104	382/106; 382/154; 382/291; 701/2
US 6885771 B2	Image recognition me	382/199	382/165; 382/203; 382/209; 382/2
US 6874420 B2	System and method fc	101/485	101/181; 101/248; 101/DIG.46; 21
US 6804386 B1	Optical member inspe	382/141	382/144; 382/145
US 6788804 B1	Optical member inspe	382/141	
US 6786732 B2	Toothbrush usage mo	434/263	
US 6748015 B2	Spread spectrum rece	375/150	375/149
US 6724811 B2	Pseudo-noise correlat	375/150	375/130; 375/134; 375/137; 375/
US 6714665 B1	Fully automated iris re	382/117	382/106; 382/190; 382/209
US 6707571 B1	Character printing me	358/1.18	347/40; 358/1.11
US 6705715 B2	Liquid container, cartr	347/87	347/7; 347/86
US 6697513 B1	Optical member inspe	382/141	382/144; 382/145
US 6695747 B2	Transmission mechan	477/123	477/174; 477/97; 701/63; 74/335
US 6665439 B1	Image recognition me	382/199	382/165; 382/197; 382/203; 382/
US 6664965 B1	Image processing dev	345/473	
US 6636625 B1	Optical member inspe	382/141	382/142; 382/149
US 6633814 B2	GPS system for navig.	701/213	
US 6596983 B2	Perimetric detection s	250/221	160/7; 220/345.1; 220/345.5; 220
US 6574558 B2	GPS receiver with cro	701/213	342/355; 342/357.01; 342/357.06
US 6535627 B1	Optical member inspe	382/141	356/239.4
US 6519358 B1	Parallax calculating a	382/154	
US 6496275 B1	Character printing me	358/1.11	369/83; 400/63; 400/65; 400/83; 7
US 6480285 B1	Multiple layer confoca	356/492	356/497
US 6477264 B1	Optical member inspe	382/141	382/143
US 6476909 B1	Optical member inspe	356/239.2	356/124; 356/239.1
US 6454400 B1	Liquid container, cartr	347/86	
US 6437778 B1	Virtual space commur	345/419	
US 6434263 B1	Optical member inspe	382/141	382/144; 382/145
US 6430310 B1	Optical member inspe	382/141	356/124; 359/798
US 6427023 B1	Optical member inspe	382/141	382/144; 382/145
US 6421609 B2	GPS receiver with cro	701/213	342/355; 342/357.01; 342/357.06
US 6400753 B1	Pseudo-noise correlat	375/134	375/130; 375/137; 375/140; 375/
US 6393046 B1	Spread spectrum rece	375/134	375/130; 375/137; 375/140; 375/
US 6375306 B1	Image printing method	347/40	347/12; 358/1.9; 400/76
US 6373485 B1	Mitigating the effects	345/421	345/622
US 6370261 B1	Vehicle surroundings	382/104	382/100
US RE37610 E	Running guide appare	340/435	180/167; 340/901; 340/903; 348/
US 6363165 B1	Optical member inspe	382/141	382/144; 382/145
US 6351554 B1	Optical member inspe	382/141	356/124; 359/798; 382/144
US 6349145 B1	Optical member inspe	382/141	382/143
US 6344930 B1	Total-focus imaging a	359/666	359/820

US 6322508 B1	Automated meat gradi	600/443	73/602
US 6320173 B1	Ball tracking system a	250/206.1	250/208.1; 473/168
US 6314363 B1	Computer human metl	701/120	342/36; 701/117
US 6314240 B1	Lens control apparatu	396/81	396/82; 396/87
US 6314200 B1	Optical member inspe	382/141	
US 6292749 B1	GPS receiver with cro	701/213	342/355; 342/357.01; 342/357.06
US 6275615 B1	Method and apparatus:	382/232	382/173
US 6236937 B1	GPS receiver with cro	701/213	342/355; 342/357.01; 342/357.06
US 6205243 B1	System and method fo	382/154	250/559.23; 356/602
US 6195609 B1	Method and system fo	701/120	342/36; 701/117; 701/301
US 6195475 B1	Navigation system for	382/312	
US 6182005 B1	Airport guidance and :	701/120	342/36; 701/117; 701/301
US 6163148 A	Sensor, drive force au	324/226	180/206; 324/207.25
US 6148097 A	Optical member inspe	382/141	382/144; 382/145
US 6125325 A	GPS receiver with cro	701/213	342/355; 342/357.01; 342/357.06
US 6093923 A	Golf driving range disl	250/206.1	250/208.1; 473/168
US 6059718 A	Endoscope form dete	600/117	600/424
US 6055335 A	Method and apparatus:	382/232	708/203
US 6044170 A	System and method fo	382/154	250/559.23; 356/613
US 6018704 A	GPS receiver	702/149	342/457; 701/213; 701/215
US 6006158 A	Airport guidance and :	701/120	340/953
US 5995650 A	System and method fo	382/154	345/419
US 5986604 A	Survey coordinate tra	342/357.12	701/213; 708/442; 708/809
US 5956028 A	Virtual space commur	715/757	345/419; 715/849
US 5867804 A	Method and system fo	701/120	340/961; 342/36; 342/456; 701/301
US 5798519 A	Method of and appara	250/206.1	244/3.1; 473/168
US 5614913 A	Optimization of survey	342/357.12	
US 5574836 A	Interactive display app	345/427	345/421; 345/9; 348/51; 715/782
US 5530420 A	Running guide appare	340/435	180/167; 340/901; 340/903; 348/1
US 5343391 A	Device for obtaining t	433/76	433/72; 433/79
US 5227985 A	Computer vision syste	702/153	345/158; 702/152
US 4975960 A	Electronic facial tracki	704/251	382/100
US 4841152 A	Continuous-resistance	250/374	250/385.1
US 4831260 A	Beam equalization me	250/354.1	378/151; 976/DIG.430
US 4827436 A	Non-contact high reso	250/559.3	356/621
US 4795909 A	High performance fror	250/385.1	250/374; 250/389
US 4789235 A	Method and system fo	351/246	351/210; 434/236
US 4707608 A	Kinesthetic charge dete	250/389	250/336.1; 250/370.09; 250/370.1
US 4580231 A	Ultrahigh resolution pi	715/513	
US 4518257 A	Optical inspection sys	356/621	408/6; 409/218
US 4446491 A	Ultrahigh resolution pi	368/48	
US 4319332 A	Method and apparatus:	342/27	340/556; 340/557; 356/5.01

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US 4287538 A Magnetic head tracking 386/78 360/70; 360/77.13; 360/77.17; 38
US 4270172 A Ultrahigh resolution pl 715/513 360/48; 396/551
US 4122525 A Method and apparatus 250/559.2; 356/398; 356/640
US 3953856 A Method and apparatus 342/458 342/125; 342/126; 342/191

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